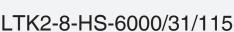
# Release date: 2020-10-08 Date of issue: 2020-10-08 Filename: 419307\_eng.pdf

# Active infrared scanner





- Mode selectable: background suppression or evaluation
- Mechanical adjustable detection range
- Adjustable timer functions
- Version for universal voltages
- Relay output

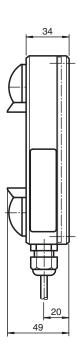
Precision sensor for extremely long detection ranges up to 6 m

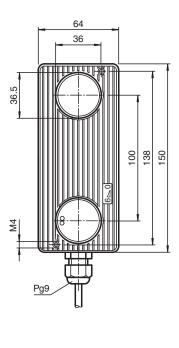


# **Function**

Diffuse mode sensors LT(K)2 are used when people, objects, or vehicles are to be detected in a precisely defined area. The devices are extremely sturdy and resistant to mechanical strain. In background evaluation operating mode, the sensors can be used with any background. In background suppression operating mode, the background serves as a reference area. This enables highly reflective objects to be reliably detected as well. In addition, this operating mode offers an option for testing.

### **Dimensions**

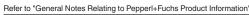






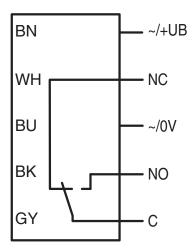
Technical Data

#### **General specifications** Detection range min. 0 ... 500 mm by background evaluation, 350 ... 500 mm by background suppression Detection range max. 0 ... 6000 mm by background evaluation, 200 ... 6000 mm by background suppression Light source **IRED** Light type modulated infrared light Operating mode switching between background suppression/evaluation Diameter of the light spot 150 mm at 6000 mm sensor range Functional safety related parameters $\mathsf{MTTF}_\mathsf{d}$ 730 a Mission Time (T<sub>M</sub>) 20 a Diagnostic Coverage (DC) 60 % Indicators/operating means Function indicator LED green: power on LED yellow: object detection Control elements Sensing range setting, programming switch for time functions, time setting **Electrical specifications** 11 ... 48 V DC / 12 ... 24 V AC Operating voltage $U_B$ 100 mA No-load supply current $I_0$ Output Switching type light/dark on selectable programmable, Factory setting: light on Signal output Relay, 1 alternator Switching voltage 240 V AC/DC Switching current 2 A Response time 100 ms De-energized delay 1200 ms $t_{off}$ Timer function Programmable on/off delay, adjustable 0.1 ... 10 s Conformity Product standard EN 60947-5-2 Compliance with standards and directives Standard conformity Emitted interference EN 61000-6-3 Standards EN 61000-6-2 without EN 61000-4-5, EN 61000-4-11 Approvals and certificates CE conformity yes **Ambient conditions** Ambient temperature -20 ... 60 °C (-4 ... 140 °F) **Mechanical specifications** Degree of protection **IP65** 5 m fixed cable Connection Material Makrolon GV30 Housing hardened plastic lens Optical face 320 g Mass

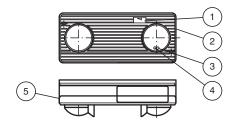


**EPPPERL+FUCHS** 

# **Connection Assignment**

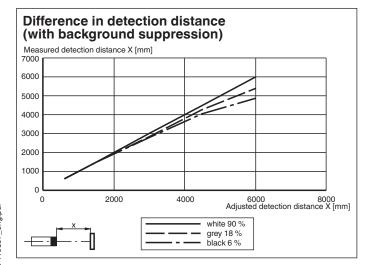


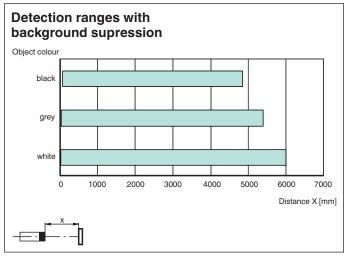
# **Assembly**

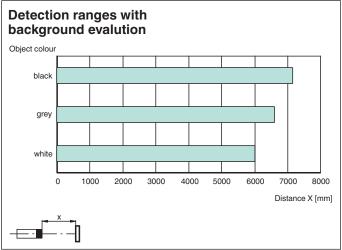


| 1 | Detection range indicator      |  |  |
|---|--------------------------------|--|--|
| 2 | Detection range adjuster       |  |  |
| 3 | Operation display Gree         |  |  |
| 4 | Function display Yellow        |  |  |
| 5 | Programming switch under cover |  |  |

# **Characteristic Curve**









# **Accessories**



Montageplatte LT

Mounting plate for sensors in the LT and FLT series

#### Alignment/Setting Instructions

Always use the object with the lowest reflection value (darkest color) for alignment purposes.

1. 1. Align the sensor to the target objects

Turn the detection range controller all the way to the right end stop (-)

(CAUTION! The controller is not protected from overturning—handle with care)

Turn the detection range controller to the left (+) until the yellow LED starts to light up

2. 2. Remove the target objects; the LED goes out (note background influences).

If the background (floor, wall) is permanently or occasionally reflective and shiny, due to moisture for example, the device must be installed in such a manner that it is rotated through  $> 5^{\circ}$  along its longitudinal axis to prevent a mirror effect.

#### Selecting the appropriate operating mode

The devices are supplied in background suppression operating mode.

The background evaluation mode should be used if:

- Objects close to the optics are detected (detection range = 0 mm)
- Reflective, shiny objects must be detected (e.g. vehicles)
- A device function test is performed by means of test input

**CAUTION!** When in background evaluation operating mode, the sensor must always be aligned with a background that remains as constant as possible. Where this is not guaranteed, background suppression operating mode must be used. The background must be located within the stipulated maximum detection range.

#### **Programming functions**

The four programming functions are set using a DIP switch, which is located on the rear of the printed circuit board. To operate, simply remove the housing cover.

The functions described can be programmed as follows:

| Switch | Description       | ON                    | OFF                    |
|--------|-------------------|-----------------------|------------------------|
| 1      | Operating mode    | Background evaluation | Background suppression |
| 2      | Switching mode    | Light on (L)          | Dark on (D)            |
| 3      | Timer function    | ON delay (GAN)        | -                      |
| 4      | Timer<br>function | OFF delay (GAB)       | -                      |



Use the potentiometer to the left of the switches to set the GAN and GAB times steplessly from 0.1 s ... 10 s.

# **Accessories**

Other suitable accessories can be found at www.pepperl-fuchs.com

# **Function Principle**

The active infrared scanners of the LT2 and LTK2 series function with the background suppression and background evaluation operating modes. The emitter and receiver are aligned at a certain angle in relation to one another. This angle can be changed and is used to determine the maximum detection range. The LT2 series operates with dc voltage and features transistor outputs; the LTK2 series operates with ac/dc voltage and features a relay output.

The devices are delivered with background suppression as the default mode.

#### **Background Suppression Operating Mode**

The sensor switches state when an object moves into or out of the detection range and is detected by the light beam. The background and/or base is ignored during this process. The sensitivity of the sensor can be adjusted so that objects beyond a certain distance are ignored. Sensors that feature this operating mode can be mounted for mobile use.

# **Background Evaluation Operating Mode**

The sensor switches state when an object moves into or out of the detection range and is detected by the light beam. However, where background evaluation is used, some form of background (such as the floor or a wall) must be present as a point of reference.

The sensor continues to switch even if no light is received from the background. Sensors with background evaluation do not have foreground suppression. This means that they can also detect objects directly in front of the lens (detection range = 0), making them particularly suited for detecting objects that are difficult to detect, especially highly reflective objects.

# **Application**

# Active infrared scanner

- · Opening impulse sensor and protection mechanism for closing edges on automatic doors and industrial doors
- · Opening impulse sensor for automatic doors
- Vehicle detection in traffic technology (e.g., individual parking space monitoring)
- · Height measurement at entrances
- · Anti-collision protection on automated guided systems